RossAutomation

Supported Editors
These setup instructions apply to any editors using the Ross Automation editor protocol.

Requirements
• Editor Interface Software Option
• Ethernet Cable

Port Connections

<table>
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<tr>
<th>Switcher</th>
<th>Editor</th>
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<tbody>
<tr>
<td>Communications</td>
<td>PERIPH Port (female)</td>
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Switcher Setup

1. Press HOME ➔ Setup ➔ Installation ➔ Com Setup ➔ Type.
   • Use the Com Port knob to select the PERIPH X port that you connected the Ross Automation editor to.
   • Use the Device knob to select Editor.
2. Press Editor Protocol.
   • Use the Device knob to select RossAuto.
3. Press Com Type.
   • Use the Type knob to select Network TCP.
4. Press Com Setting.
5. Use the Client/Server knob to select Server.
   • In the Local IP Address field, enter 0.0.0.0.
   • Leave the Local IP Port field as is.
6. Press HOME ➔ Confirm.

Note: The Editor remote enable, or button, must be turned on for the editor to control the switcher (Home ➔ More ➔ Remote Enables).

Device Setup
Ensure the port on the Ross Automation editor that is connected to the switcher is configured for Network TCP.

Compatibility

<table>
<thead>
<tr>
<th>Editor</th>
<th>Version</th>
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<tbody>
<tr>
<td>RossAutomation</td>
<td>--</td>
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