

Start Here!

1 Before You Begin: Set Up Your Furio Live Robot

For information about setting up your Furio Live robot, refer to the appropriate instruction sheet:

- **Furio SE Live - Setting Up the Track and Robot (5100DR-051-xx)**
- **Furio S2 Live - Setting Up the Track and Robot (5100DR-061-xx)**

Setting Up the Robot Control Components

2 Set Up the Robot Control Components

IMPORTANT: This section describes how to connect robot control components to form a CAN data network. The components must be connected in the order described. The CAN data cable from the robot connects to the **EMERGENCY STOP box (step 2b)**, and then the network extends through each component, terminating at the **joystick module (step 2g)**.

Tip: If the robot has no track and no lift, there is no **foot pedal box** and no **foot pedals**.

2a Unpack the robot control components and arrange them at the operator position:

- Place the **EMERGENCY STOP box**, **control console**, and **joystick module** on the control table.
- If the robot includes a track and/or lift, place the **foot pedal box** and the **foot pedals** on the floor, beneath the control table.

2b Find the **CAN data cable** in the cable bundle from the robot, and connect it to the **robot port** on the **EMERGENCY STOP box**.

Tip: The **robot port** has a drawing of a robotic dolly.

IMPORTANT: Position the **EMERGENCY STOP box** where the operator can easily reach the **EMERGENCY STOP** button.

2c On the **EMERGENCY STOP box**, twist the **EMERGENCY STOP** button clockwise to disengage it.

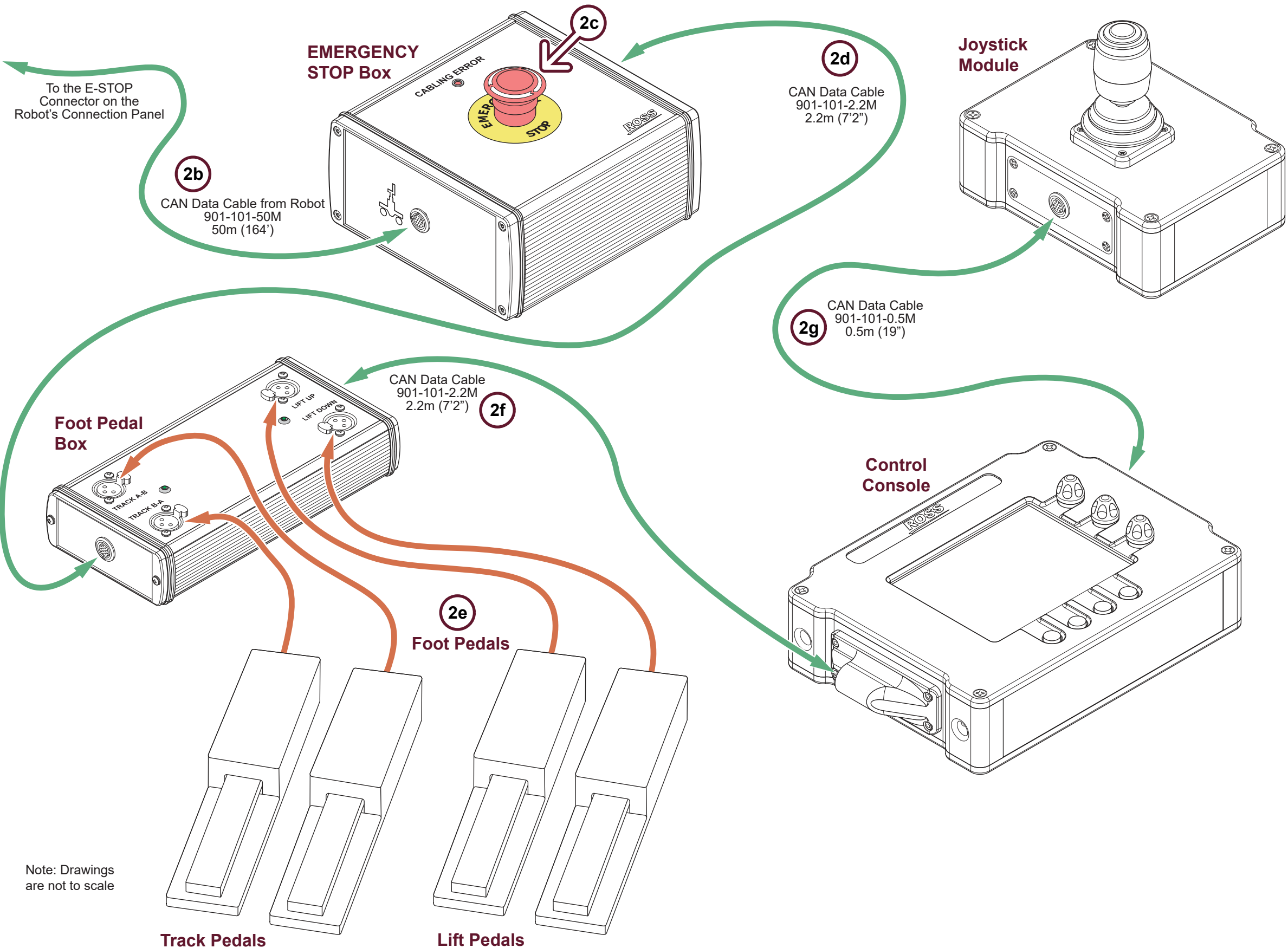
2d Connect a **2.2m (7'2") CAN data cable (901-101-2.2M)** from the **EXPANSION PORT** on the **EMERGENCY STOP box** to any **CAN connector** on the **foot pedal box** (if equipped), or to any **CAN connector** on the **control console** (if there are no pedals).

2e Connect any required **foot pedal cables** to the **foot pedal box**, and then position the **Foot Pedals (LIFT UP, LIFT DOWN, TRACK A-B, TRACK B-A)** to suit your personal preferences.

2f If there are foot pedals, connect a **2.2m (7'2") CAN data cable (901-101-2.2M)** from the **foot pedal box** to any **CAN connector** on the **control console**.

2g Connect the **0.5m (19") CAN data cable (901-101-0.5M)** from the **control console** to the **joystick module**.

2h Find the **AC power supply cable** in the cable bundle from the robot, and connect it to the **facility's AC power**.



Setting Up the Focus / Zoom Module

3

Set Up the Focus/Zoom Module

- 3a Unpack the focus/zoom module and place it on the control table.
- 3b Find the 50m (164') lens control cable (901-205-50) in the cable bundle from the robot, and connect it to the LENS port on the focus/zoom module.
- 3c On the focus/zoom module, set the lens selection switch for the type of lens you are controlling (CANON or FUJINON).

Setting Up the Operator Monitor(s)

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Set Up the Operator Monitor(s)

Typically, the operator position has two monitors; one showing live video from the camera that the operator is controlling, and one showing program video.

Note: Video monitors are not included with the Furio Live system.

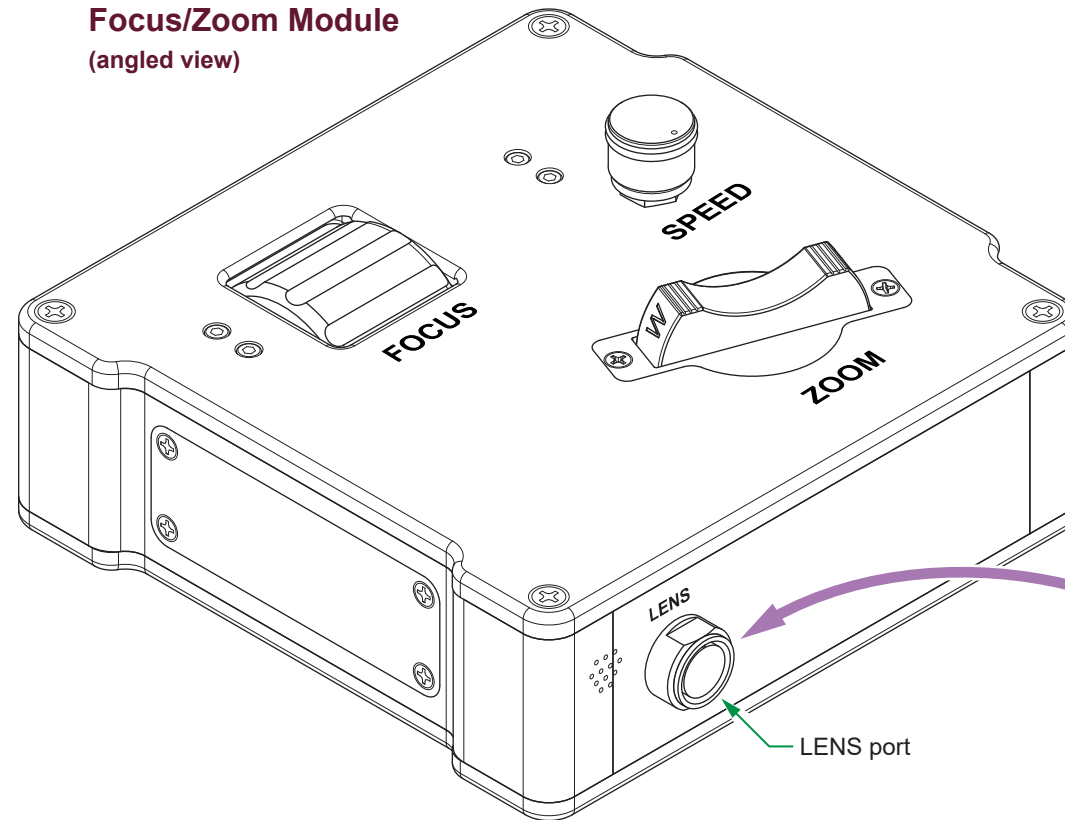
Next Steps: Configuring and Operating the System

5

Configure and Operate the Furio Live System

For detailed instructions, refer to the following instruction sheet:
 • *Furio Live - Configuring and Operating the System, using Joystick Controls (5100DR-065-xx)*

Focus/Zoom Module
(angled view)

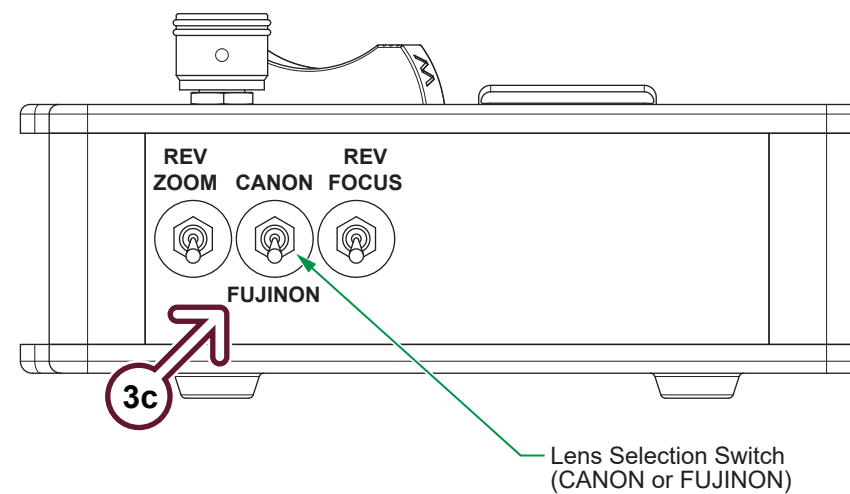


Lens Control Cable
901-205-50
50m (164')

3b

To the Camera/Lens on the Dolly
(via lens adapter cable)

Focus/Zoom Module
(rear view)



3c

Lens Selection Switch
(CANON or FUJINON)

Note: Drawings are not to scale