

## RossTalk XPression

The RossTalk XPression device enables OverDrive to use the RossTalk protocol to control external applications or devices in the OverDrive system. The RossTalk protocol is a plain text based protocol that you can use to send commands to external devices through the RossTalk XPression device.

### Remote Device Port Configuration Settings

Use the following procedure to configure a RossTalk XPression device on the Caprica Server:

1. Use the current version of **DashBoard** software to connect to your **Caprica Server**.
2. In the **DashBoard Tree View**, double-click the **Port Configuration** node of your Caprica Server.
3. In the **Port Configuration Summary** table, double-click a **REMOTE#** in the **Port** column.
4. In the **Configure REMOTE#** panel, click **RossTalk**.
5. Click **RTalkXPN**.
6. Click **Network Settings**.
7. Use the following settings to configure the **Network Settings** for your RossTalk XPression device:
  - **Ethernet Role** — Client
  - **Remote IP Address** — enter 0.0.0.0 to send RossTalk commands through all network interface cards of a Caprica Server. Enter a specific IP address to only send RossTalk commands through the network interface card associated with the entered IP address.
  - **Remote Port** — 7788
  - **Local IP Address** — 0.0.0.0
  - **Local Port** — 0
  - **Protocol** — TCP
8. Click **Apply Changes** to save the RossTalk XPression device settings.
9. Click **Done** to close the Configure REMOTE# panel.

#### For More Information on...

- configuring remote devices for OverDrive systems that contain a Caprica Server, refer to the *Caprica User Guide*.

### Sending RossTalk Commands from Caprica

In Caprica, you can create a Custom Control that sends a RossTalk command to the external device associated with a selected RossTalk XPression device. Custom Controls can send pre-configured RossTalk commands or typed in commands up to 32 characters in length.

#### For More Information on...

- creating Caprica custom controls, refer the “Creating Custom Control Macros” section in the *OverDrive Installation and Configuration User Guide*.
- supported RossTalk commands, refer to the *RossTalk-Commands (4802DR-403-09)* document.

### Compatibility

Automation	Version
OverDrive	15.1
Caprica Server	1.4a

### Contacting Technical Support

Technical Support is staffed by a team of experienced specialists ready to assist you with any question or technical issue.

Ross Video has technical support specialists strategically located around the globe to ensure a prompt response to technical inquiries. Our primary technical support center is located in Ottawa, Ontario, Canada. In addition, we have offices in The United Kingdom (London), Australia (Sydney), and Singapore with satellite locations in New York City, The Netherlands, and China. As we expand our presence globally, we are constantly evaluating other key locations to have a local technical support specialist in order to better service our customers.

#### North America

Our North America center located in Ottawa, Ontario, Canada and is open Monday to Friday 8:30 a.m. to 6:00 p.m. EST, with 24/7/365 on-call service after hours.

Our telephone number is: +1-613-686-1557

Toll free within North America: +1 833-859-0499

## EMEA

Our EMEA center is open Monday to Friday 8:30 a.m. to 5:00 p.m. GMT. After hours support is provided by our North America location.

Our telephone number is: +44 (0)1189502446

International toll free: +800 3540 3545

If the local support specialist is not available, your call will be transferred automatically to our North America center.

## Australia

Our Sydney, Australia office is located in Alexandria, NSW.

Our local support telephone number is: 1300 007 677

If the local support specialist is not available, your call will be transferred automatically to our North America center.

## Online

E-mail: [techsupport@rossvideo.com](mailto:techsupport@rossvideo.com)

Website: open a support request using the link <https://support.rossvideo.com/> to open a support request.

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